



Effect of external torques on the satellite angular motion

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Plan

- Introduction
- Gravity gradient torque
- Geomagnetic field
- Solar radiation pressure
- Shadow models
- Atmospheric drag

Introduction

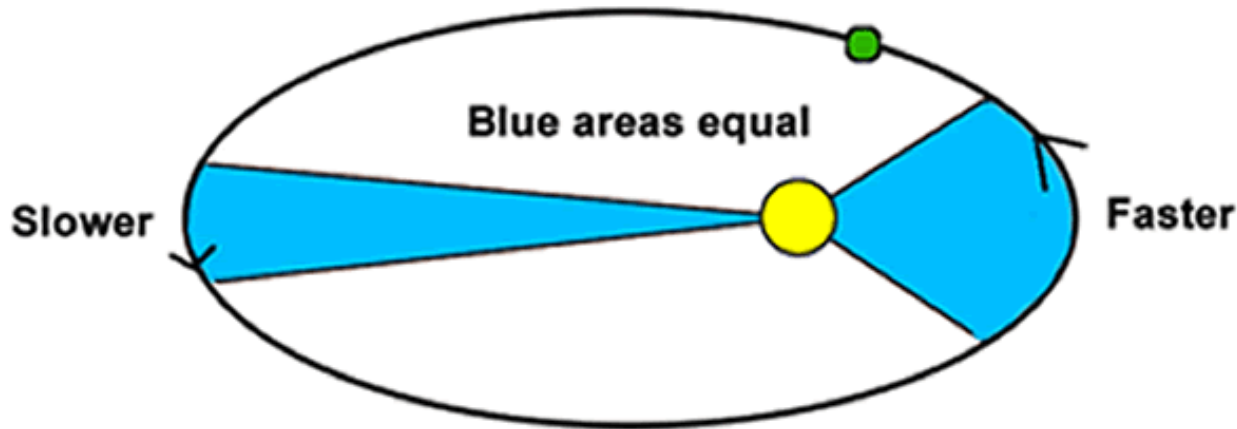
External disturbances

- depend on the satellite location
- depend on the velocity
- change with time

We want to predict satellite motion with high accuracy

Kepler's laws

1. The orbit of a planet is an ellipse with the Sun at one of the two foci.
2. A line segment joining a planet and the Sun sweeps out equal areas during equal intervals of time.

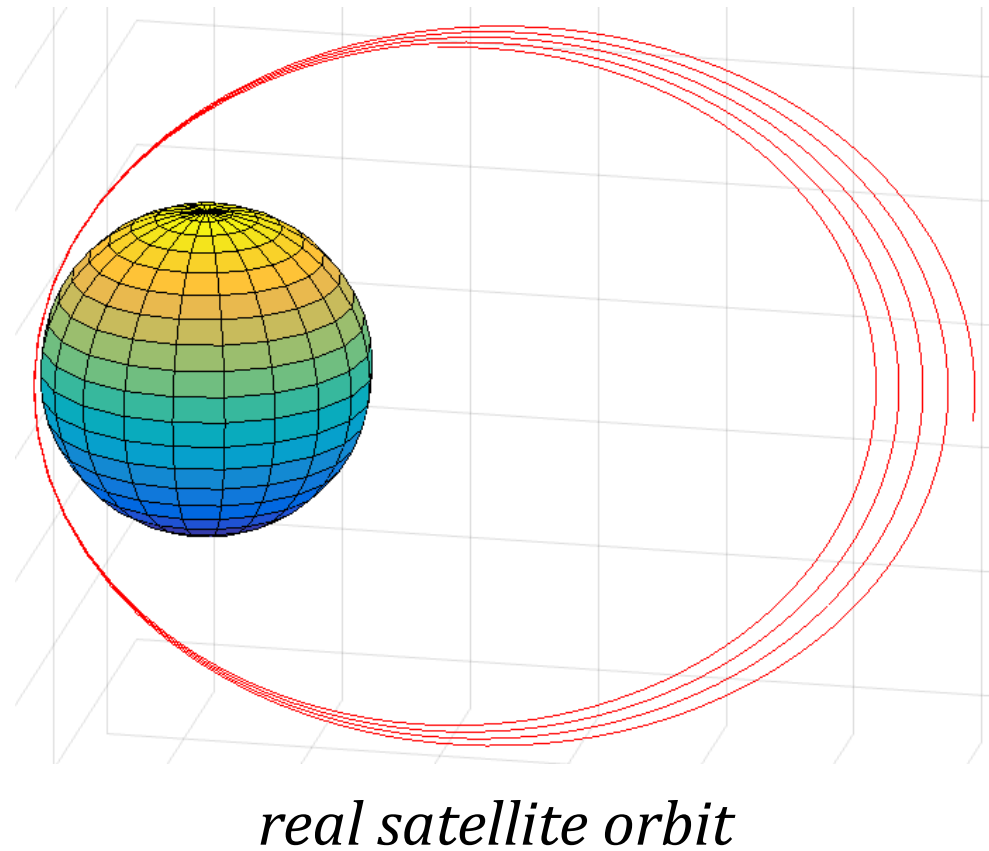
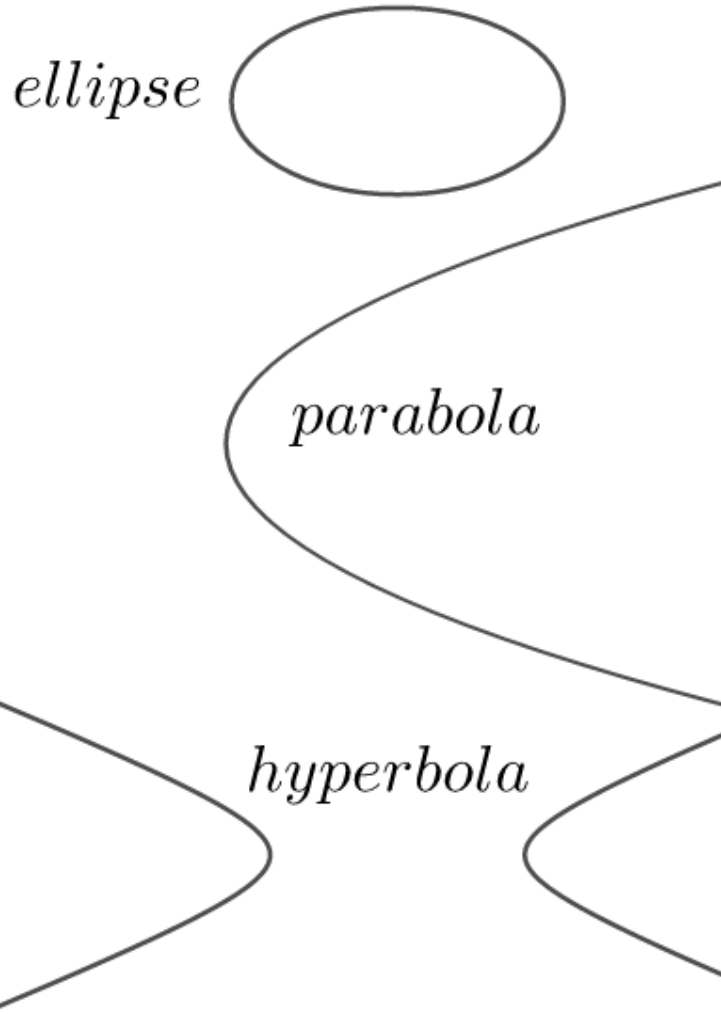


3. The square of the orbital period of a planet is proportional to the cube of the semi-major axis of its orbit.

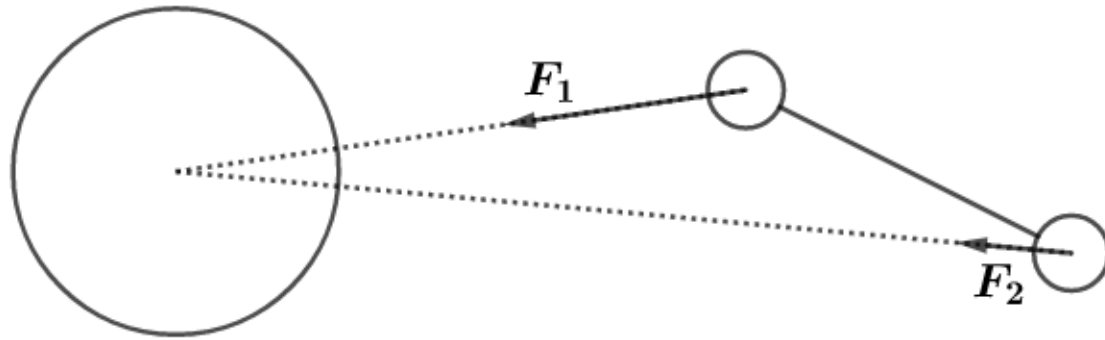
$$\frac{T_1^2}{T_2^2} = \frac{a_1^3}{a_2^3}$$

Keplerian orbits

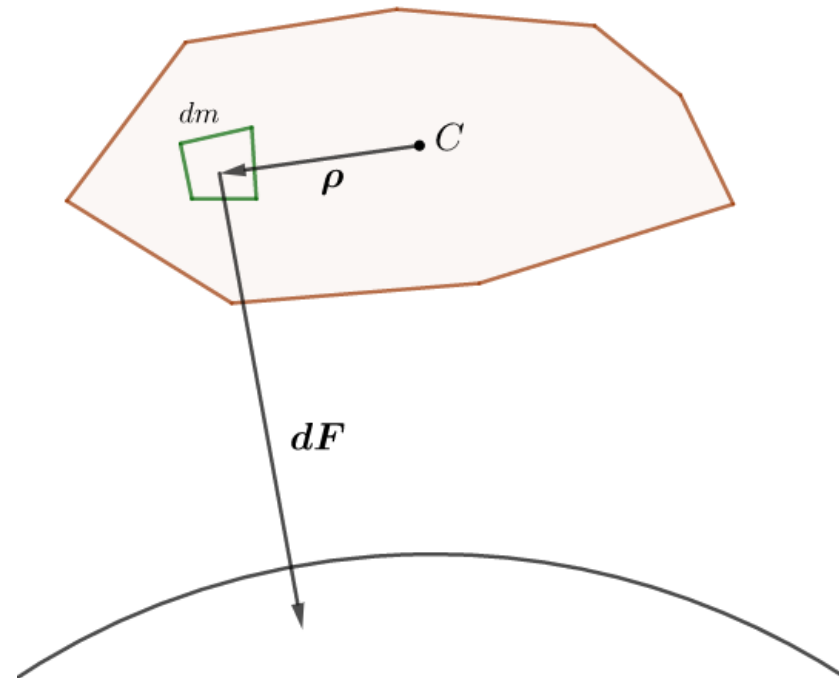
$$F = G \frac{m_1 m_2}{r^2} \quad \text{– Newton's law of universal gravitation}$$



Gravity gradient torque



$F_1 > F_2$ — torque appears, satellite rotates



$$d\mathbf{M}_{grav} = \boldsymbol{\rho} \times d\mathbf{F} = \boldsymbol{\rho} \times \frac{\mu\mathbf{r}}{r^3} dm$$

Gravity gradient torque

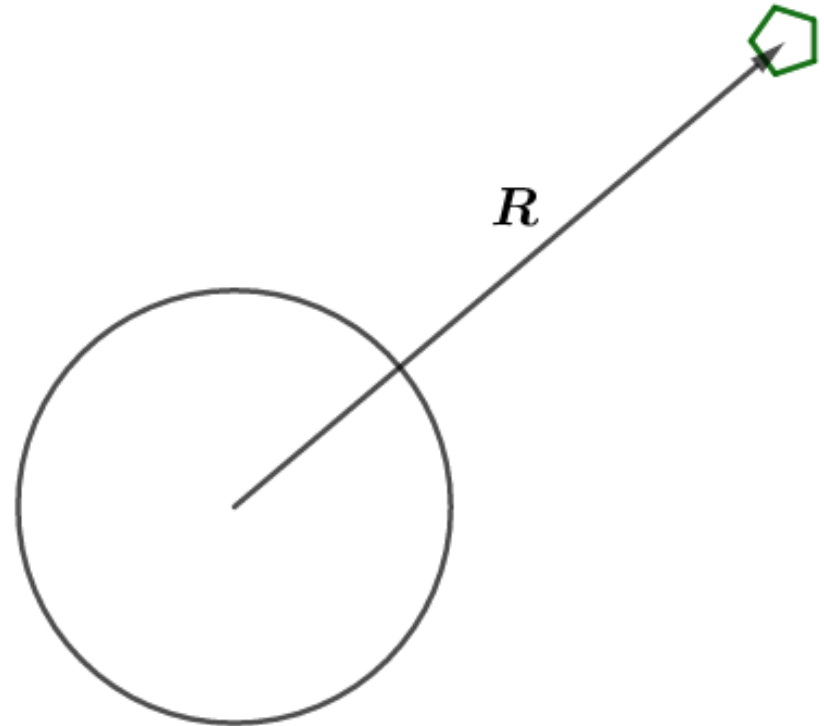
$$\mathbf{M}_{grav} = \int_V \boldsymbol{\rho} \times \frac{\mu \mathbf{r}}{r^3} dm$$

$$\mathbf{M}_{grav} = 3 \frac{\mu}{R^5} \mathbf{R} \times \mathbf{J} \mathbf{R} \text{ — expression for the gravity gradient torque}$$

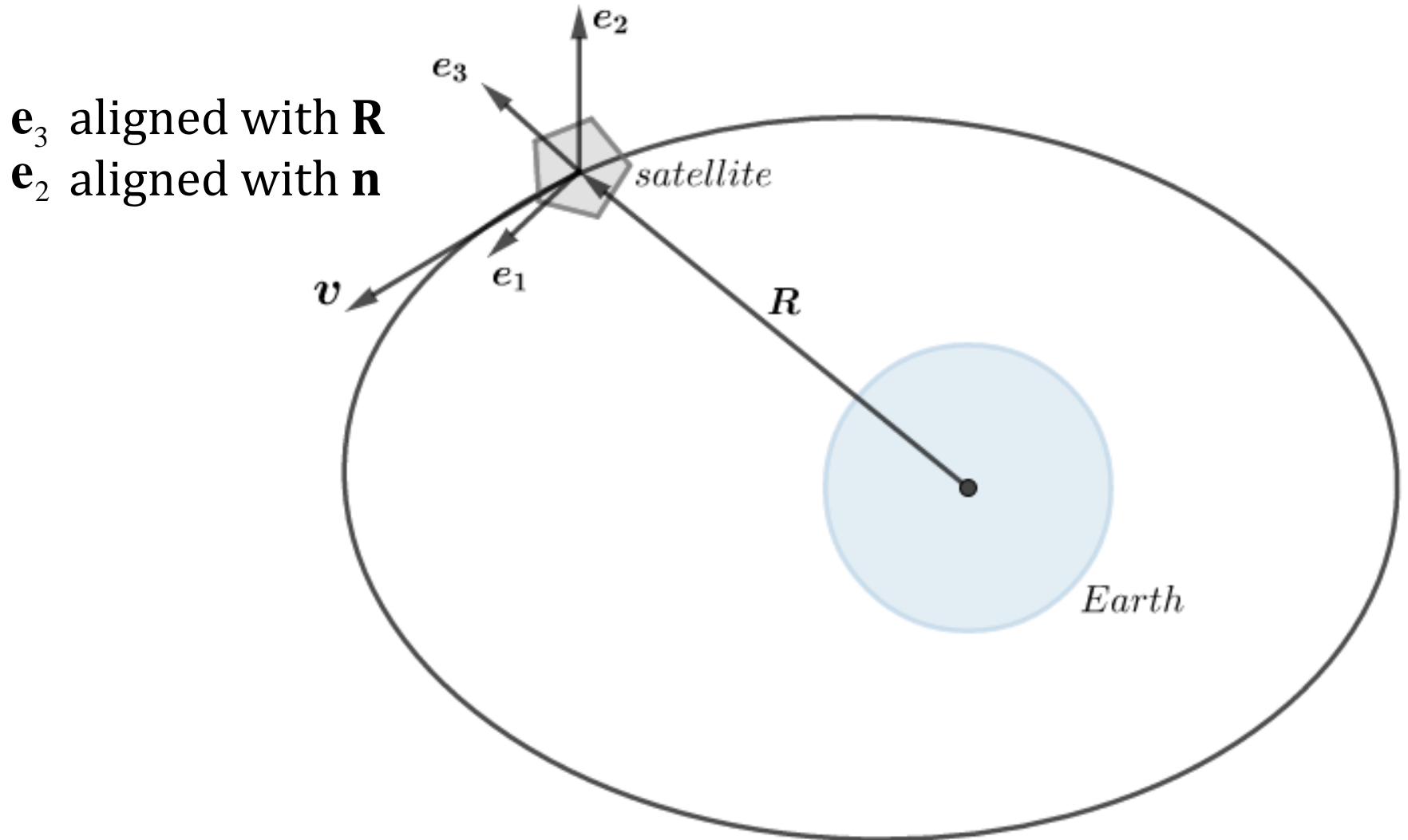
$\mu = 3.968 \cdot 10^{14} \text{ m}^3/\text{s}^2$ – Earth's gravity parameter

\mathbf{J} — inertia tensor

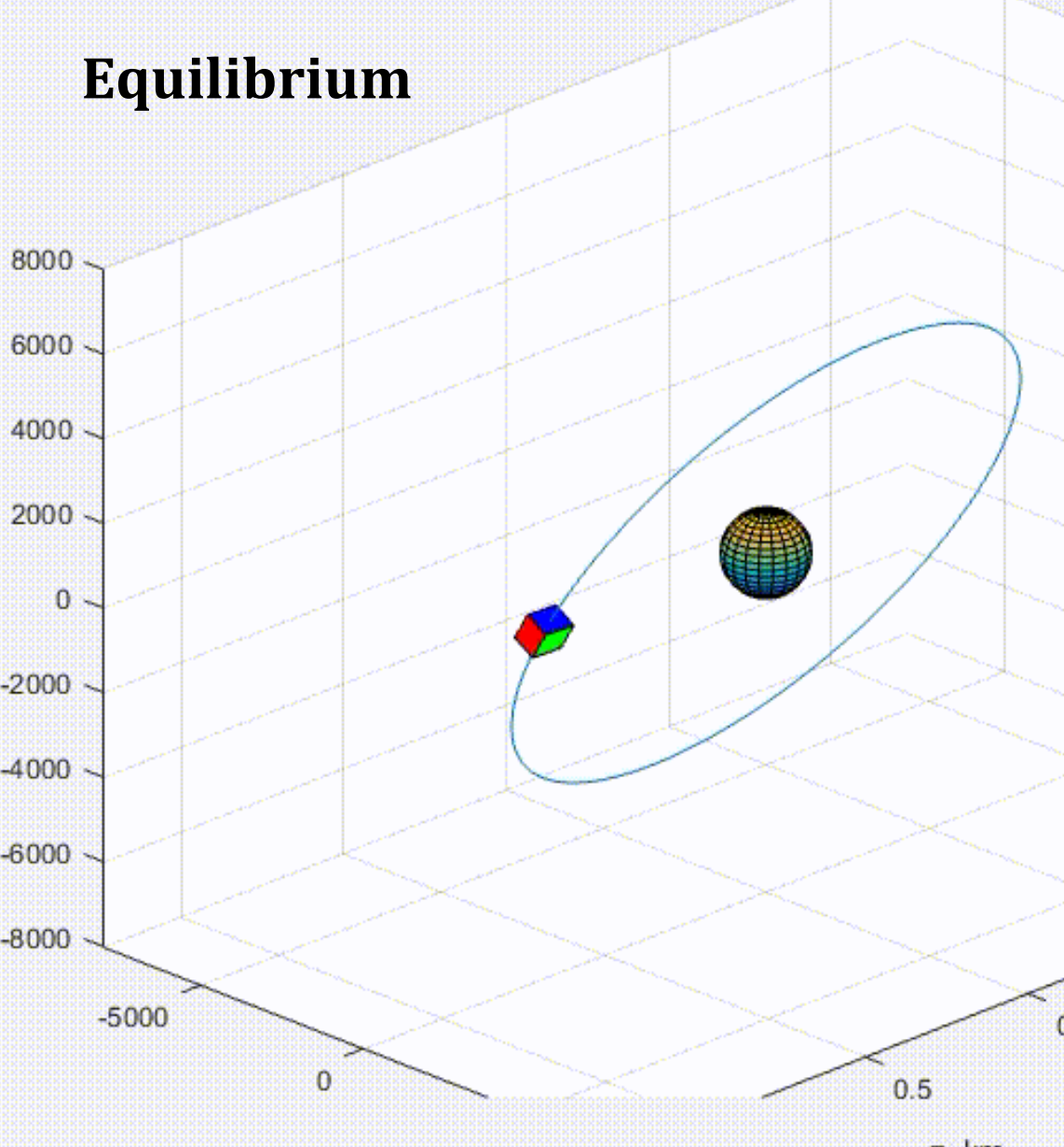
Radius-vector \mathbf{R} - vector from the center of Earth to the center of mass of satellite



Orbital coordinate system

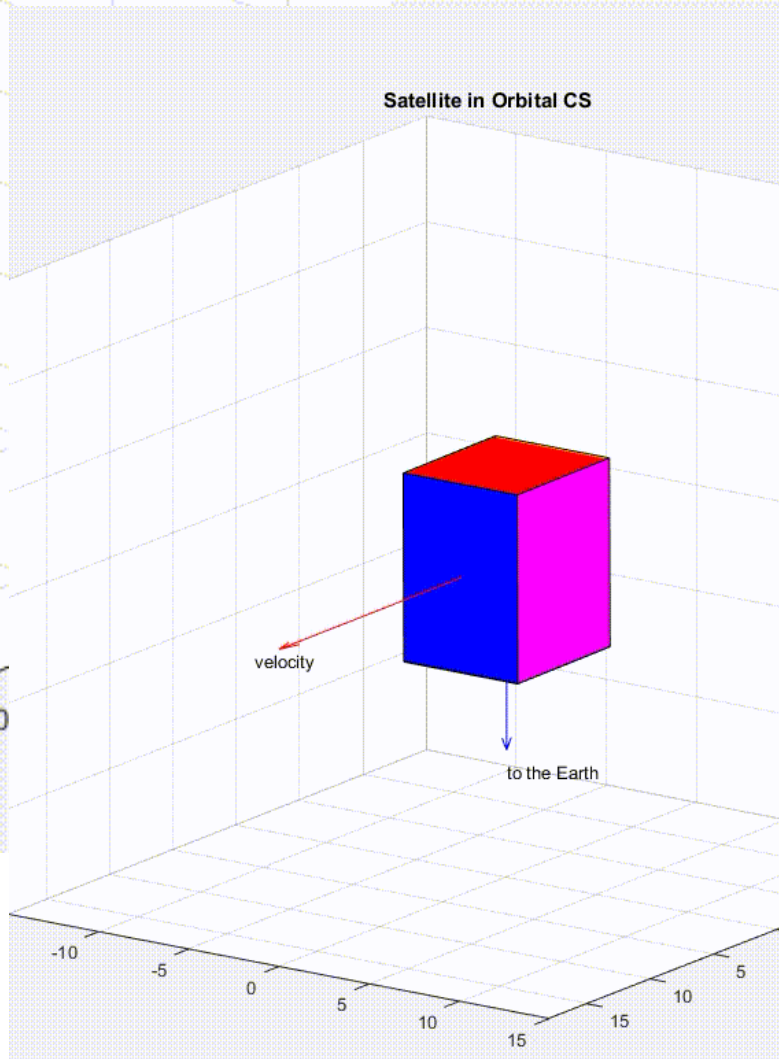


Equilibrium

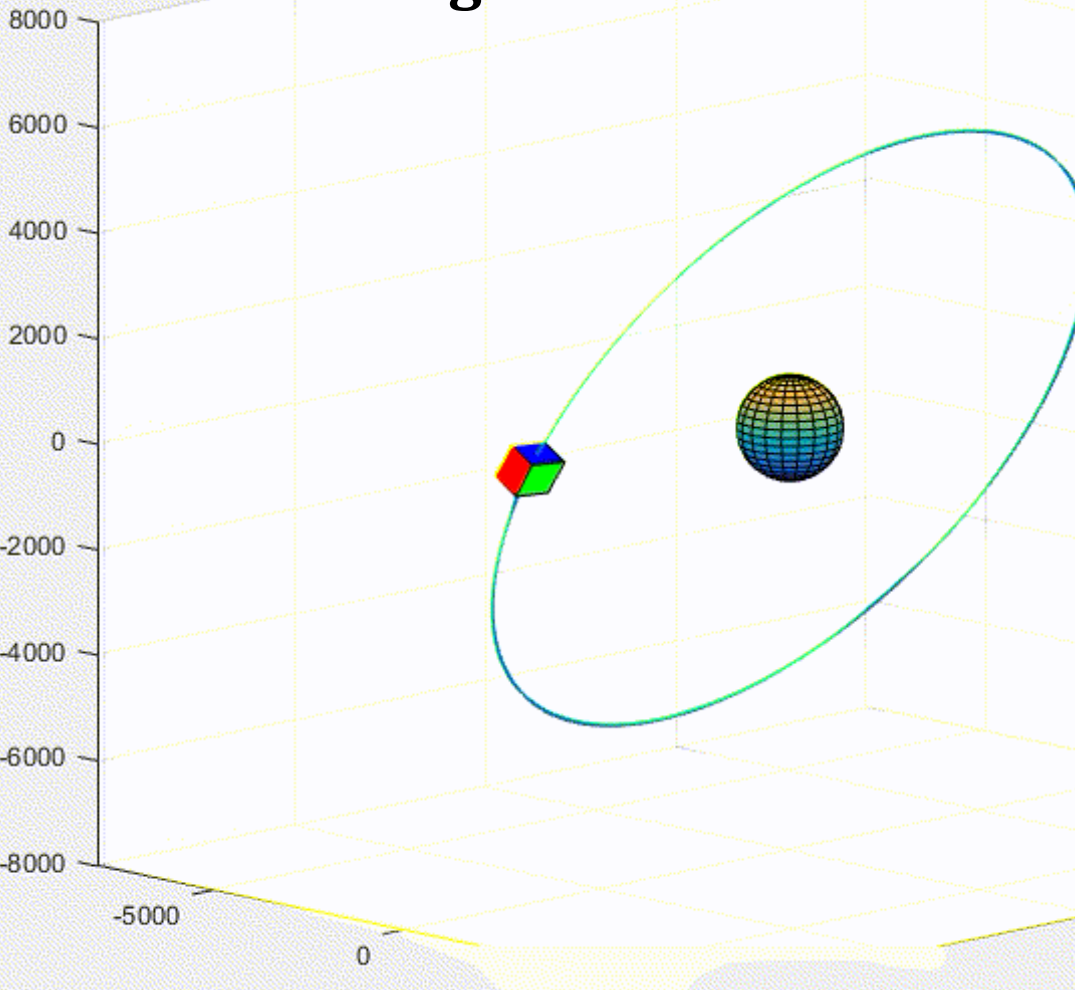


Satellite in Inertial CS

Satellite in Orbital CS

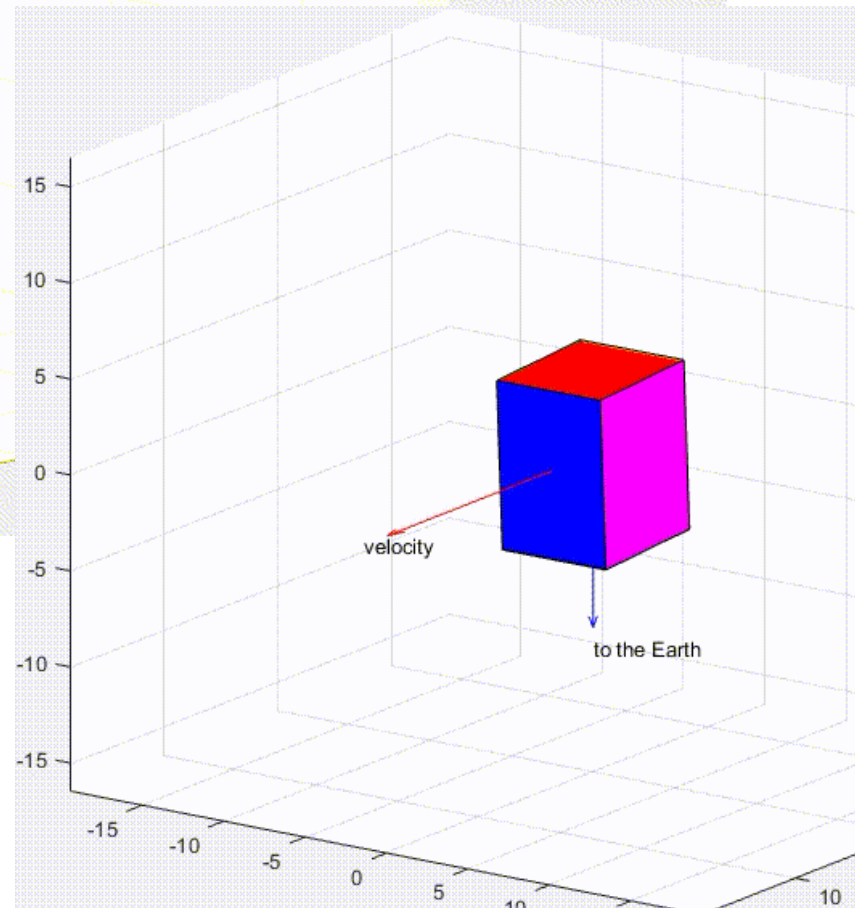


Motion in general case



Satellite in Inertial CS

Satellite in Orbital CS

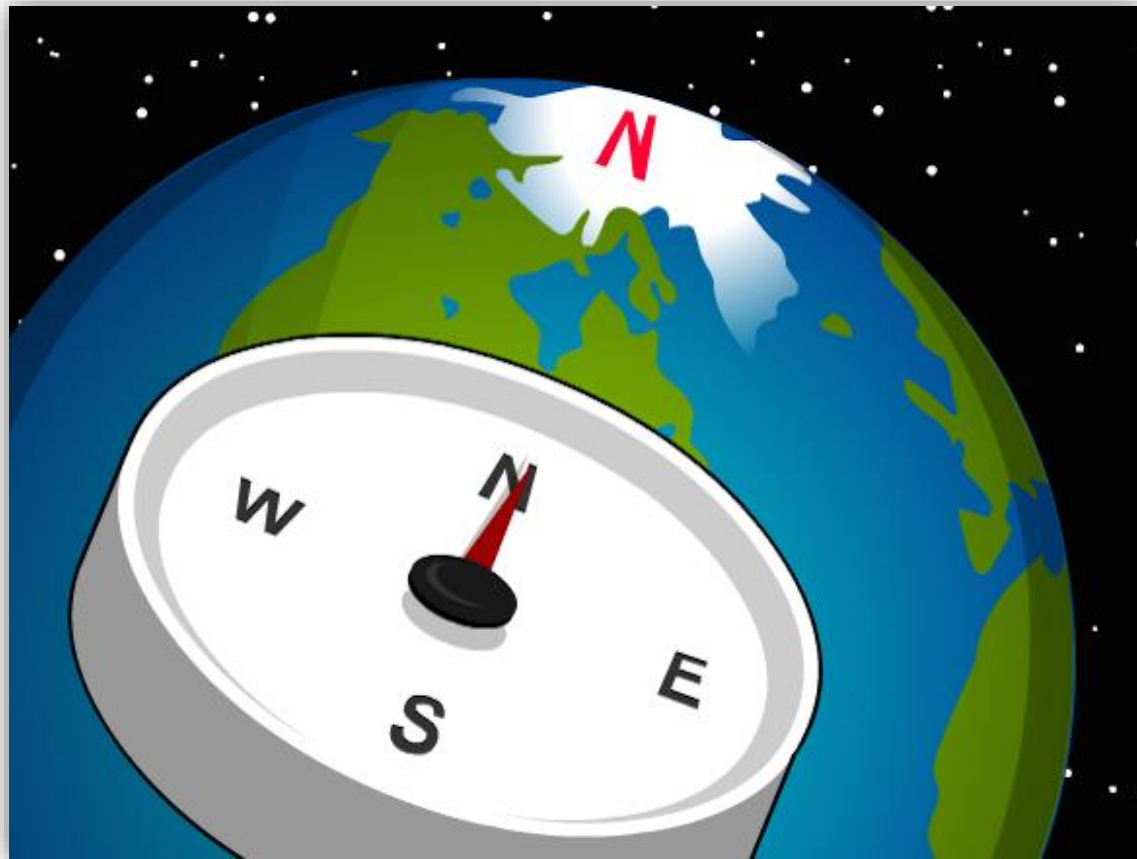


Geomagnetic field

$$\mathbf{M}_{magn} = \mathbf{m} \times \mathbf{B}$$

B - vector of magnetic induction

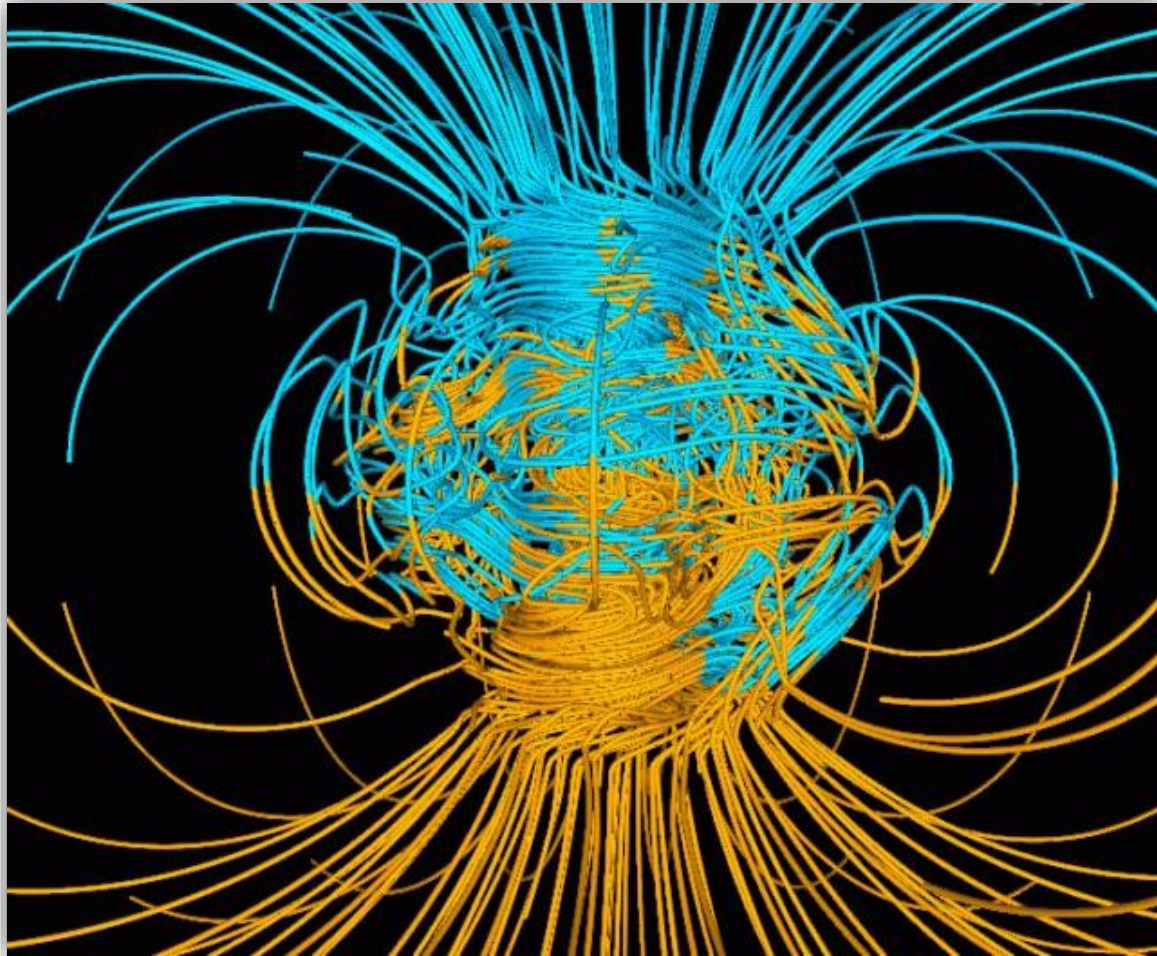
m - dipole moment



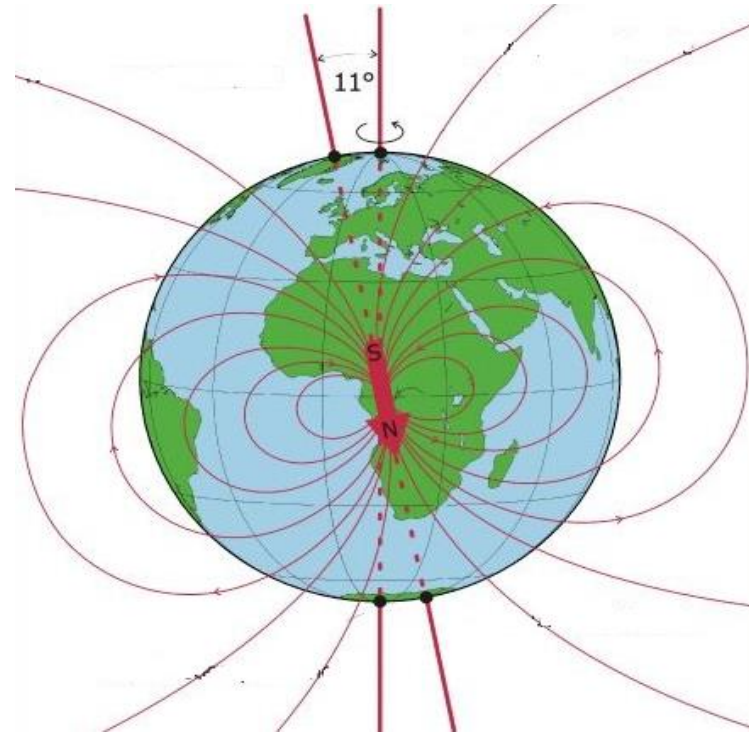
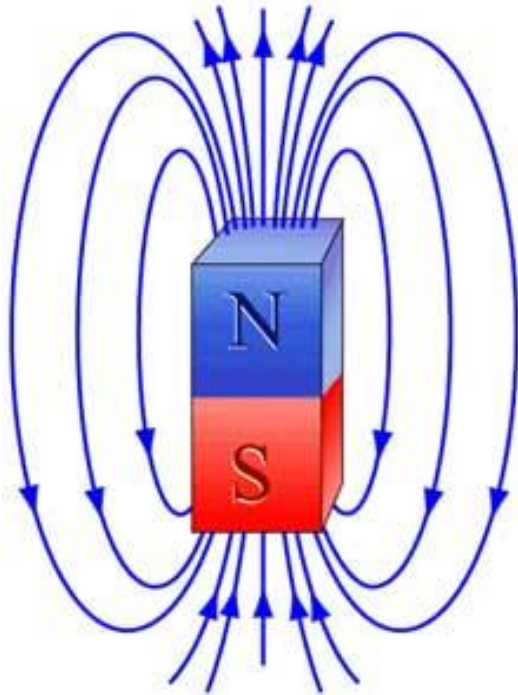
Real geomagnetic field

$\mathbf{B} = \mu_0 \nabla V$ — expression for vector of magnetic induction

$$V = -R \sum_{i=1}^k \left(\frac{R}{r} \right)^{i+1} \sum_{n=0}^m \left(g_n^m(t) \cos m\lambda_0 + h_n^m(t) \sin m\lambda_0 \right) P_n^m(\cos \vartheta_0)$$



Geomagnetic field



$$\mathbf{B} = -\frac{\mu_e}{R^5} (\mathbf{k}R^2 - 3(\mathbf{k}\mathbf{R})\mathbf{R})$$

$\mu_e = 7.812 \cdot 10^{15} \text{ m}^3 \cdot \text{kg} \cdot \text{s}^{-2} \cdot \text{A}^{-1}$ — Earth's magnetic constant

There are two ways of calculating the vector \mathbf{k} (unit vector co-directional with the magnet)

Geomagnetic field

- **direct dipole model**

Dipole is antiparallel to Earth rotation axis

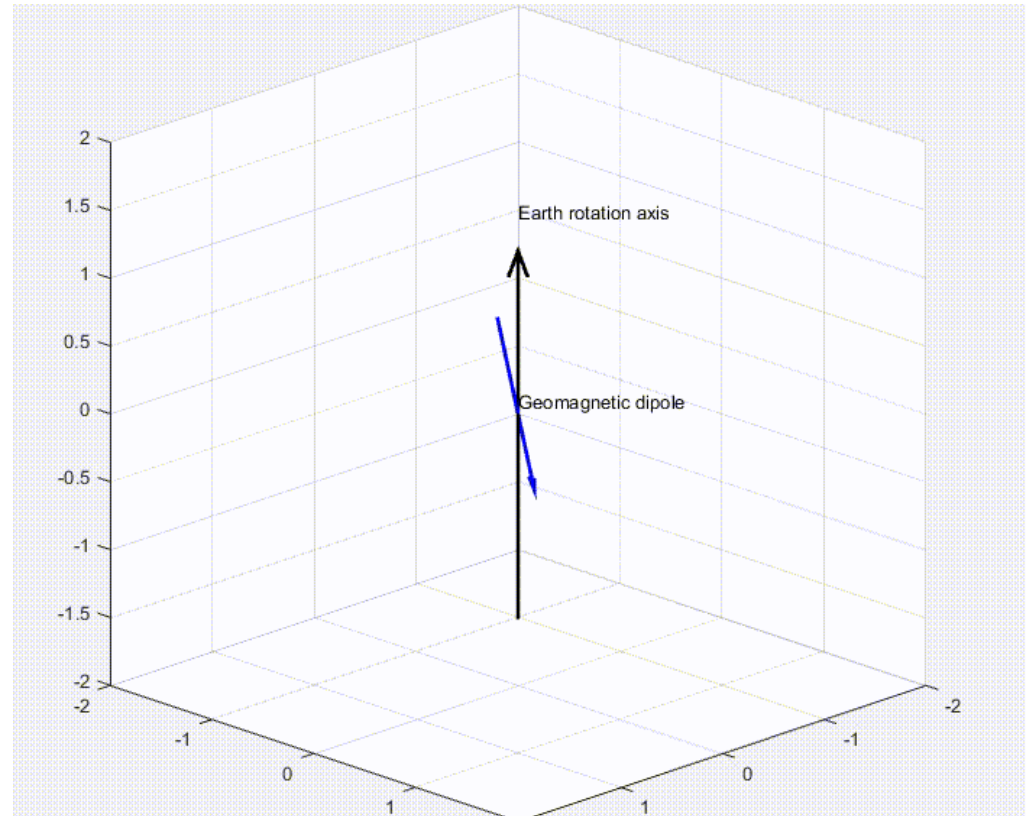
$$\mathbf{k} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

- **inclined dipole model**

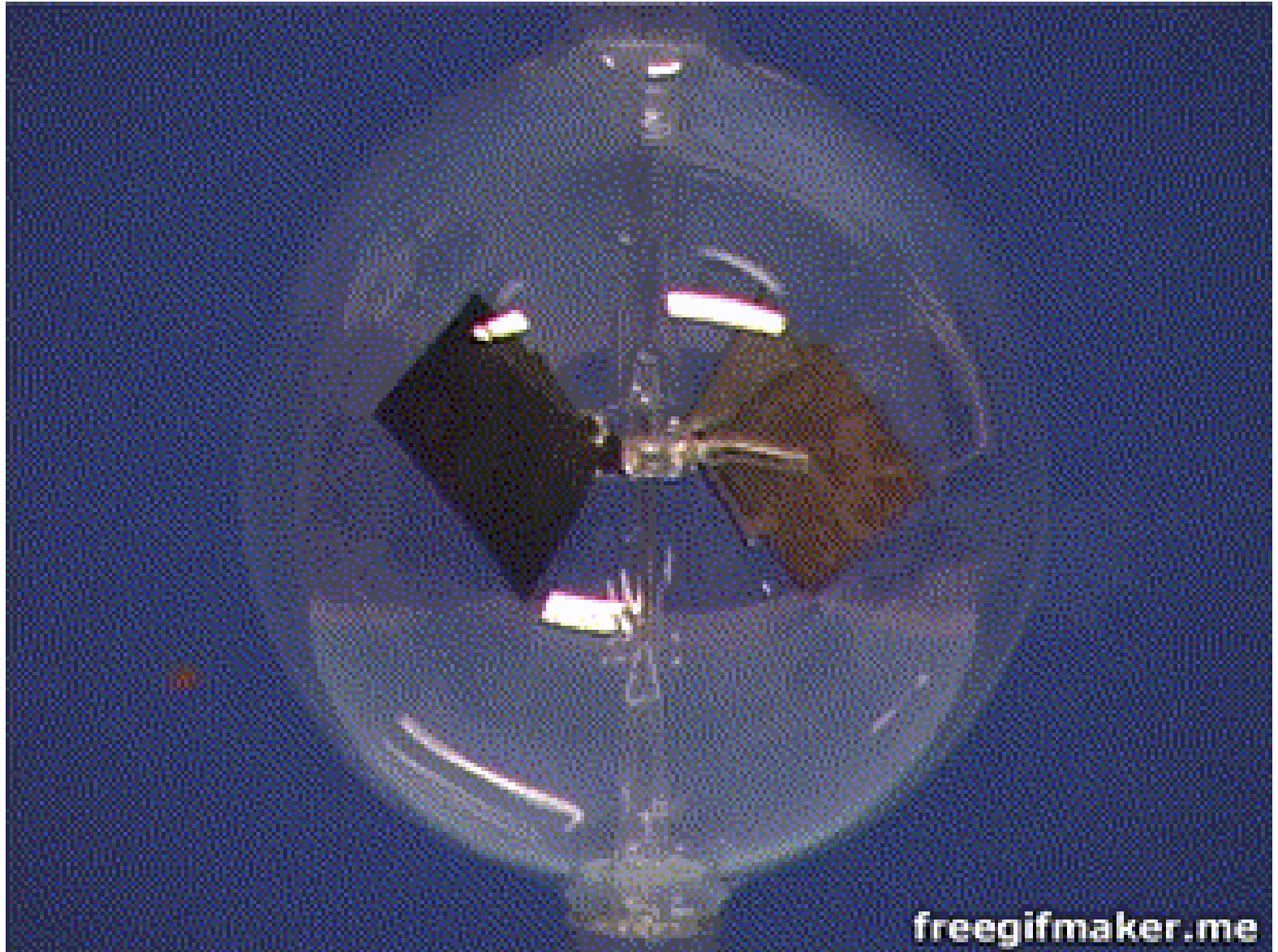
Dipole is tilted

$$\mathbf{k} = \begin{pmatrix} \cos \lambda \sin \theta \\ \sin \lambda \sin \theta \\ \cos \theta \end{pmatrix}$$

$\theta \approx 168.3^\circ$, $\lambda_0 \approx -71.88^\circ$, $\lambda = \lambda_0 + \omega_{Earth} t$ – changes with time



Radiation pressure



Solar radiation pressure

The total force of solar radiation pressure acting on flat surface

$$\mathbf{F}_{sun} = -S \frac{\Phi_0}{c} (\mathbf{r}_s, \mathbf{n}) \left((1 - \alpha) \mathbf{r}_s + 2\alpha\mu(\mathbf{r}_s, \mathbf{n})\mathbf{n} + \alpha(1 - \mu) \left(\mathbf{r}_s + \frac{2}{3} \mathbf{n} \right) \right)$$

$$\mathbf{r}_s = \frac{\mathbf{R}_s}{|\mathbf{R}_s|} \text{ - unit vector of the Sun direction}$$

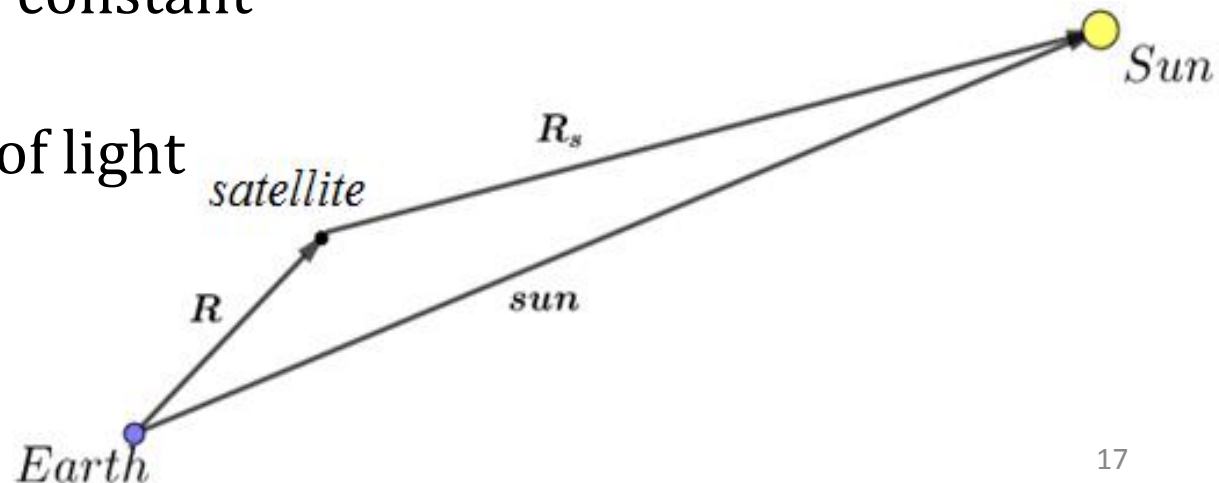
α , μ - the characteristics of the reflecting surface

\mathbf{n} - unit vector of the normal to the satellite surface

$$\Phi_0 = 1367 \frac{W}{m^2} \text{ - solar constant}$$

$$c = 3 \cdot 10^8 \frac{m}{s} \text{ - speed of light}$$

S - surface area

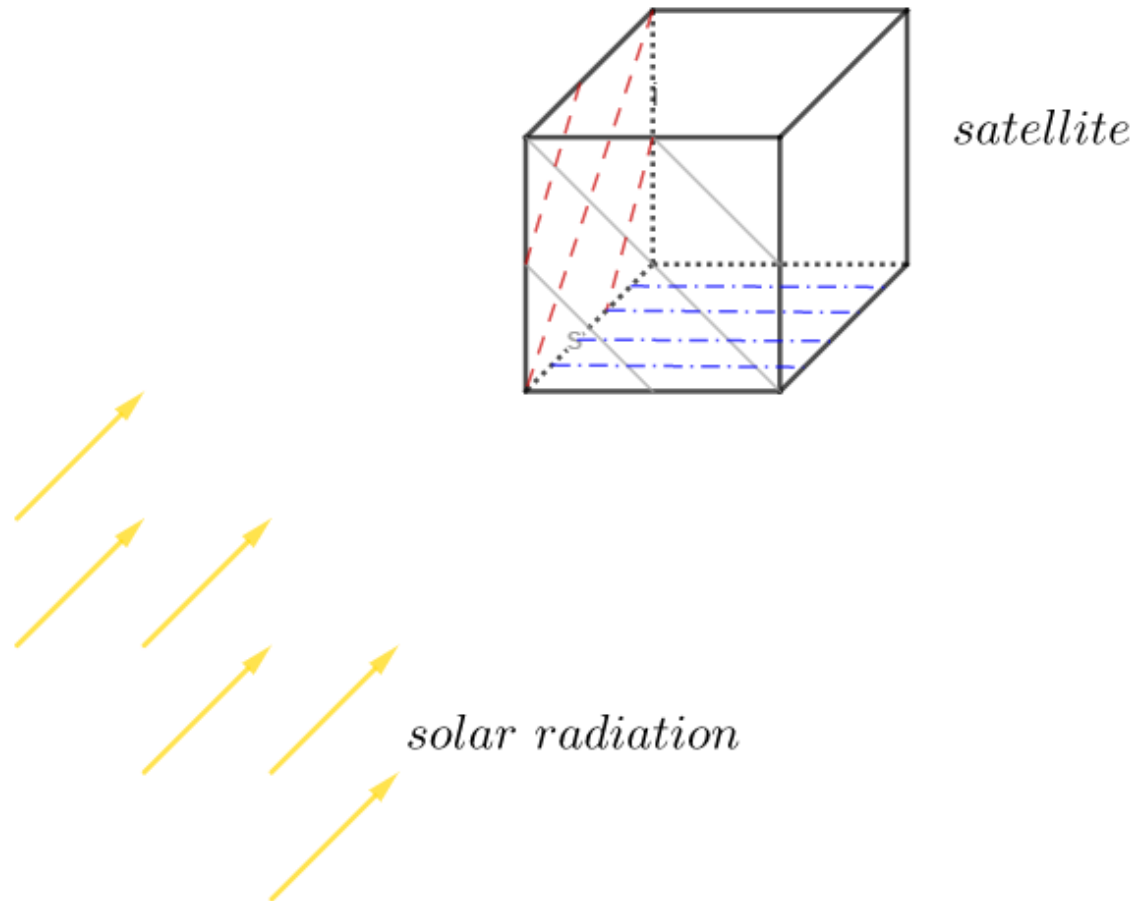


Solar radiation pressure

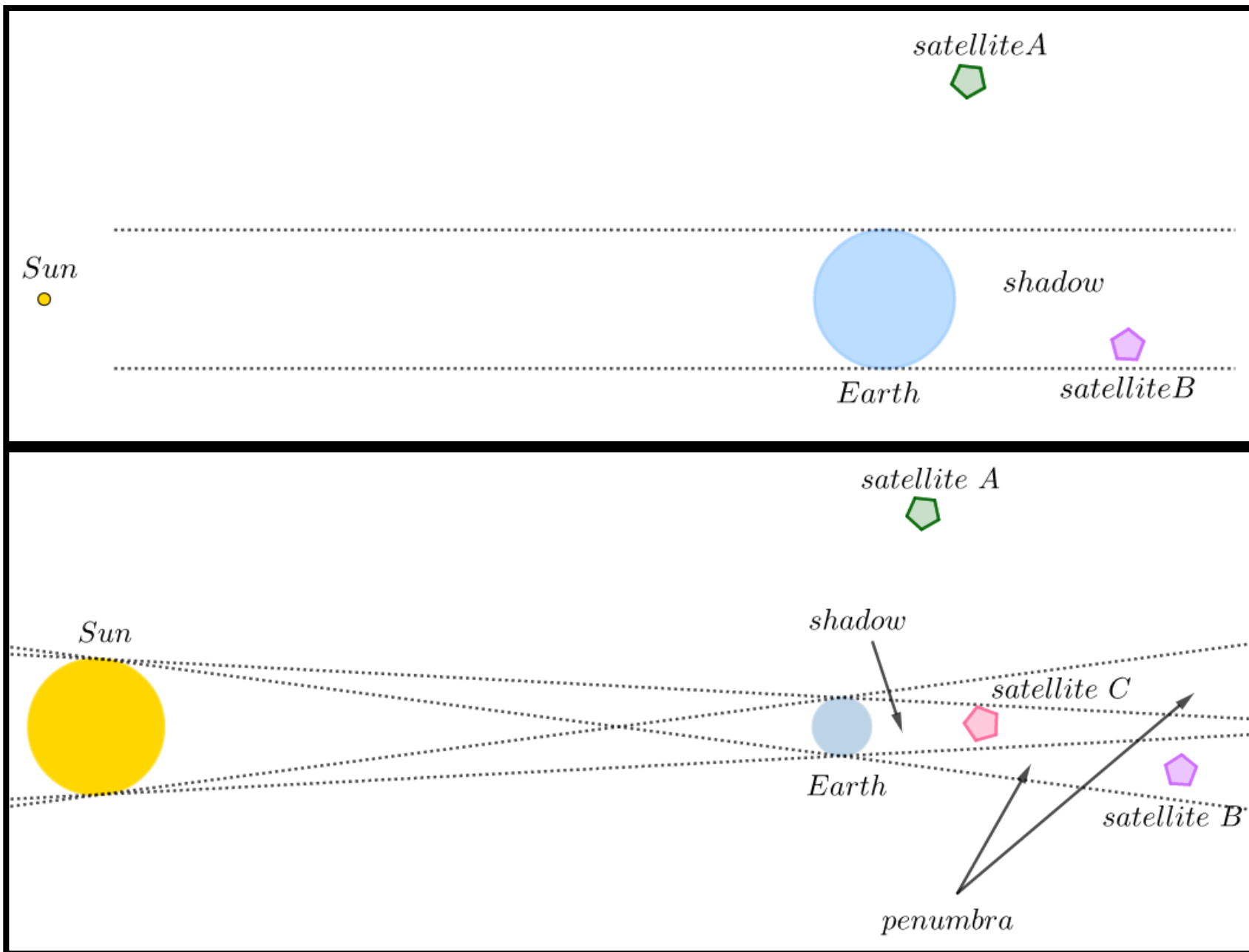
Not all surfaces are lightened in a complex shape satellite

Example: cubic satellite

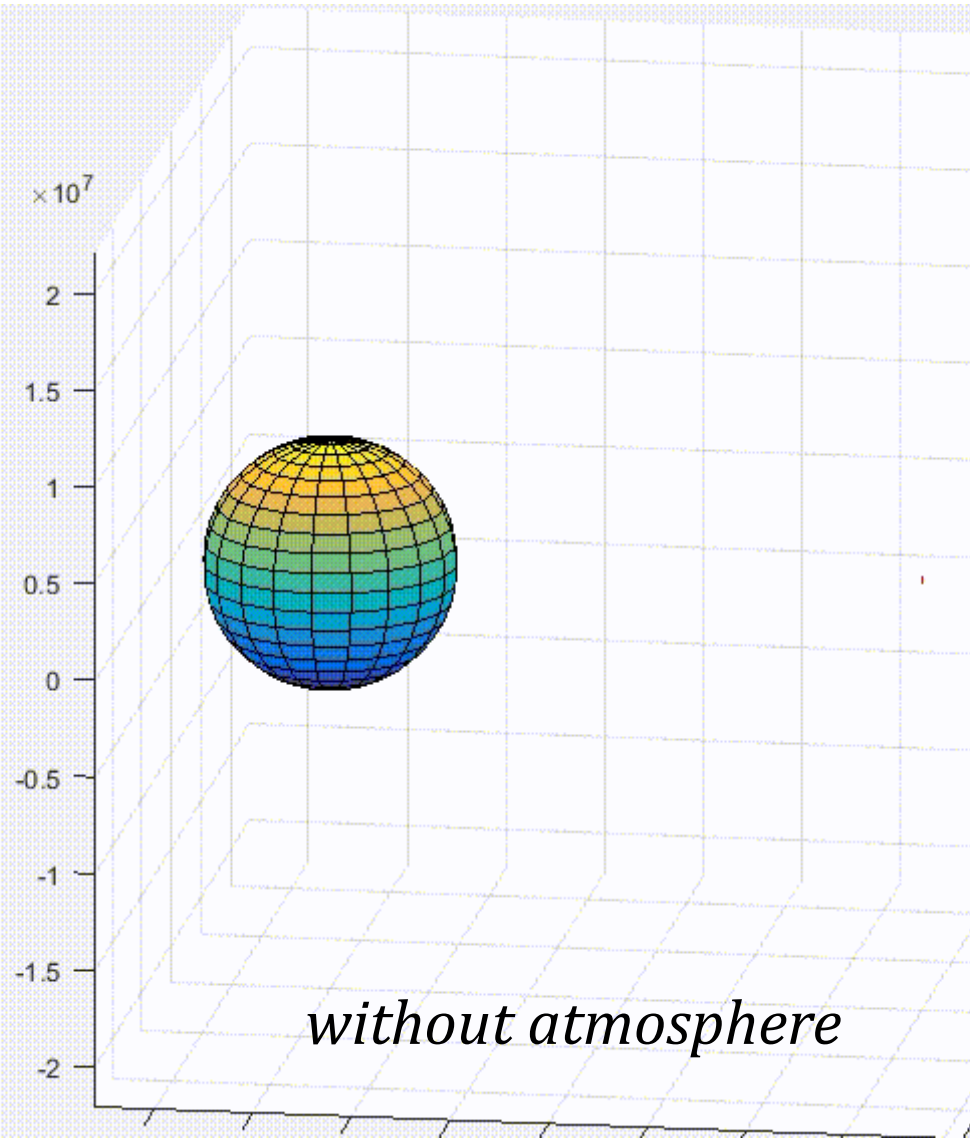
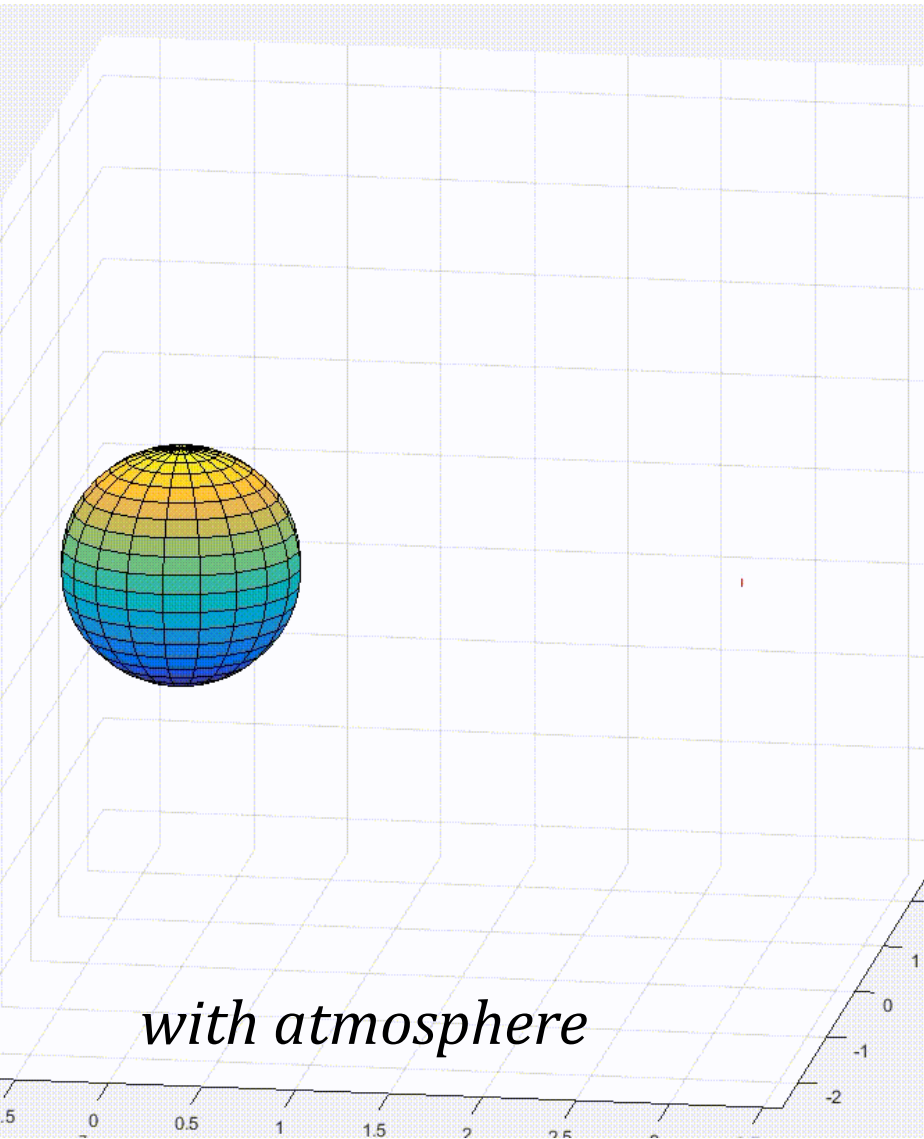
We should consider only three lightened surface



Shadow models



Atmospheric drag



Atmospheric drag

1) The air resistance force (frontal drag)

$$\mathbf{F}_{atm} = -\frac{1}{2} \rho_a |\mathbf{V}| \mathbf{V} C_D S$$

2) The force acting on the elementary part of the surface area dS

$$d\mathbf{F}_{atm} = -\rho_a \left((1 - \varepsilon_{atm}) (\mathbf{V}, \mathbf{n}) \mathbf{V} + 2\varepsilon_{atm} (\mathbf{V}, \mathbf{n})^2 \mathbf{n} + (1 - \varepsilon_{atm}) \alpha_{atm} (\mathbf{V}, \mathbf{n}) \mathbf{n} \right) dS$$

$\varepsilon_{atm}, \alpha_{atm} \in (0, 1)$ – the characteristics of the surface

Atmospheric drag

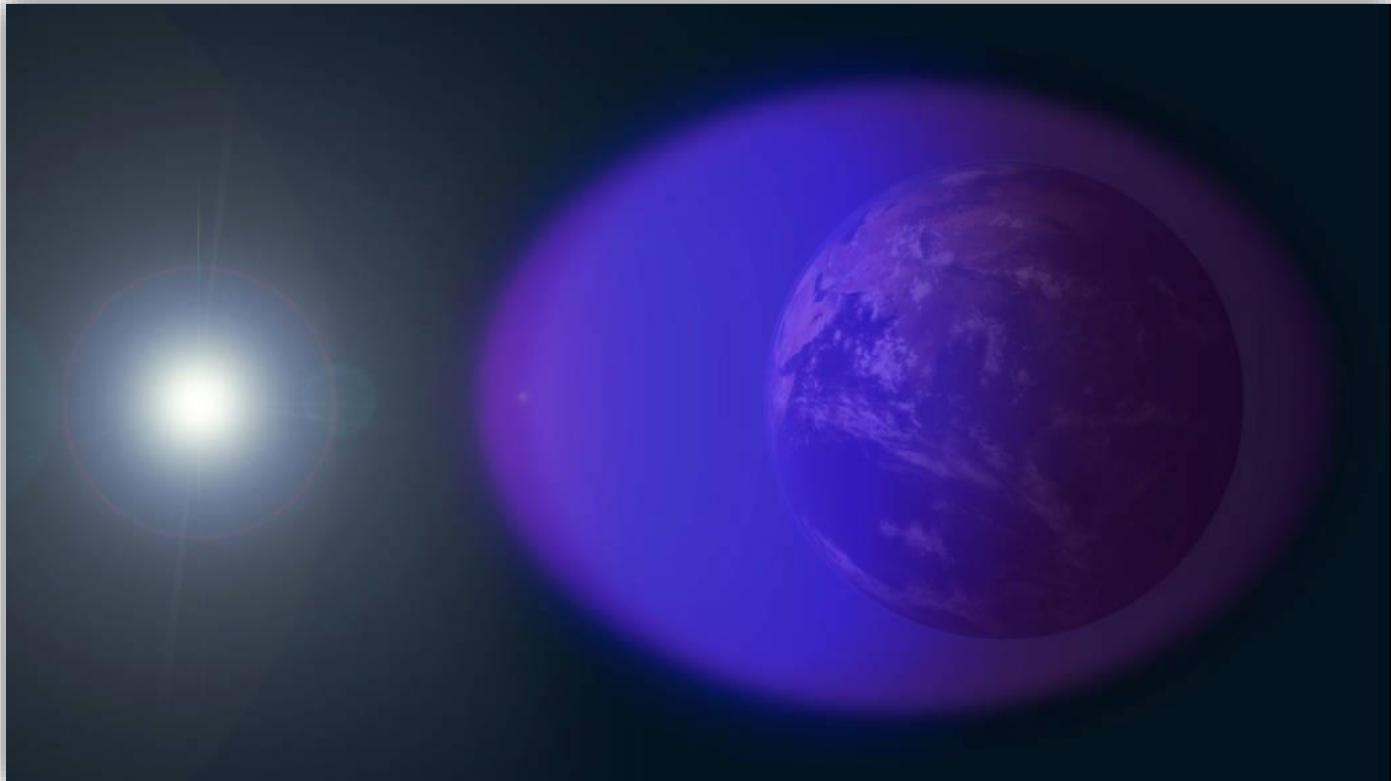
Density distribution models

1) Constant density $\rho_a = \text{const}$

2) Exponential density distribution model $\rho_a = \rho_0 \exp\left(\frac{H - h_0}{\xi}\right)$

ρ_0, H, h_0, ξ - some parameters

3) CIRA



Summary

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Thank you for listening!

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